

Amendments to the Claims:

Please amend the claims as follows:

1-16. (canceled)

17. (new) A displacement control method, comprising:

a calculating step of calculating a displacement control signal for driving a proportional electromagnetic valve based on a displacement command; and

an adjusting step of adjusting a displacement angle of a hydraulic device by driving the proportional electromagnetic valve with the displacement control signal calculated in the calculating step, and applying a displacement control pressure generated from the proportional electromagnetic valve to a displacement adjusting device, wherein

the displacement control signal is calculated in the calculating step based on the required displacement control pressure, the required displacement control pressure being based on a reference characteristic representing a relationship between a required displacement control pressure required to provide a displacement angle corresponding to a displacement command and a required displacement control signal required for the proportional electromagnetic valve to generate the required displacement control pressure, the calculating step further comprising

calculating based on the reference characteristic a minimum-side displacement control pressure corresponding to a minimum-side displacement control signal required to achieve a minimum-side displacement that is set in advance for learning and calculating a maximum-side displacement control

pressure corresponding to a maximum-side displacement control signal required.
to achieve a maximum-side displacement that is set in advance for learning,

detecting a pressure generated from the proportional
electromagnetic valve when the proportional electromagnetic valve is driven
with the minimum-side displacement control signal as a first measured pressure,

detecting a pressure generated from the proportional
electromagnetic valve when the proportional electromagnetic valve is driven
with the maximum-side displacement control signal as a second measured
pressure,

calculating as learned values a first difference between the
minimum-side displacement control pressure and the first measured pressure,
and a second difference between the maximum-side displacement control
pressure and the second measured pressure,

in response to an operator-generated displacement command,
calculating a correction amount based on the first and second differences and the
operator-generated displacement command,

correcting a required displacement control pressure required to
provide a displacement angle corresponding to the operator-generated
displacement command with the correction amount; and

calculating the displacement control signal based on the corrected
required displacement control pressure with reference to the reference
characteristic.

18. (new) A displacement control method, comprising:

a calculating step of calculating a displacement control signal for driving a proportional electromagnetic valve, based on a displacement command; and

an adjusting step of adjusting a displacement angle of a hydraulic device by driving the proportional electromagnetic valve with the displacement control signal calculated in the calculating step, and applying a displacement control pressure generated from the proportional electromagnetic valve to a displacement adjusting device, wherein

the displacement control signal is calculated in the calculating step, based on the displacement command, referring to a reference characteristic representing a relationship between the displacement command and a required displacement control signal required for the proportional electromagnetic valve to generate a required displacement control pressure required to provide a displacement angle corresponding to the displacement command, the calculating step further comprising:

calculating a minimum-displacement-side control signal used for learning and a maximum-displacement-side control signal used for learning based on the reference characteristic, and

detecting pressures generated from the proportional electromagnetic valve when the proportional electromagnetic valve is driven with the minimum-displacement-side control signal and the maximum-displacement-side control signal as first and second measured pressures, respectively;

calculating, based on a relationship between the minimum-displacement-side and maximum-displacement-side control signals and the first and second measured pressures, a minimum displacement control signal for causing the proportional electromagnetic valve to generate a displacement control pressure corresponding to a minimum displacement angle, and a maximum displacement control signal for causing the proportional electromagnetic valve to generate a displacement control pressure corresponding to a maximum displacement angle;

calculating a first difference between the minimum displacement control signal and the minimum-displacement-side control signal used for learning, and a second difference between the maximum displacement control signal and the maximum-displacement-side control signal used for learning;

generating, based on the reference characteristic and the first and second differences, a learned characteristic representing a relationship between a displacement command and a required displacement control signal corresponding to the displacement command;

calculating based on the learned characteristic a correction amount based on the displacement command; and

correcting with the correction amount the displacement control signal calculated in the calculating step based on the displacement command referring to the reference characteristic, with the correction amount.

19. (new) A displacement control method according to claim 17, wherein;
when detecting the first measured pressure, the displacement control
signal is increased from a minimum displacement so as to set the minimum-
displacement-side control signal for learning, for use in detection of the first
measured pressure; and

when detecting the second measured pressure, the displacement control
signal is reduced from a maximum displacement so as to set the maximum-
displacement-side control signal for learning, for use in detection of the second
measured pressure.

20. (new) A displacement control method according to claim 18, wherein:
when detecting the first measured pressure, the displacement control
signal is increased from a minimum displacement so as to set the minimum-
displacement-side control signal for learning, for use in detection of the first
measured pressure; and

when detecting the second measured pressure, the displacement control
signal is reduced from a maximum displacement so as to set the maximum-
displacement-side control signal for learning, for use in detection of the second
measured pressure.

21. (new) A displacement control device, comprising:

a calculating unit, the calculating unit calculating a displacement control signal for driving a proportional electromagnetic valve based on a displacement command; and

an adjusting unit, the adjusting unit adjusting a displacement angle of a hydraulic device by driving the proportional electromagnetic valve with the displacement control signal calculated by the calculating unit, and applying a displacement control pressure generated from the proportional electromagnetic valve to a displacement adjusting device, wherein with reference to a reference characteristic representing a relationship between a required displacement control pressure required to provide a displacement angle corresponding to a displacement command and a required displacement control signal required for the proportional electromagnetic valve to generate the required displacement control pressure, the calculating unit calculates the displacement control signal based on the required displacement control pressure,

wherein

the calculating unit, based on the reference characteristic, calculates a minimum-side displacement control pressure corresponding to a minimum-side displacement control signal required to achieve a minimum-side displacement that is set in advance for learning, and a maximum-side displacement control pressure corresponding to a maximum-side displacement control signal required to achieve a maximum-side displacement that is set in advance for learning,

the displacement control device further comprises a pressure detector which detects a pressure generated from the proportional electromagnetic valve when the proportional electromagnetic valve is driven with the minimum-side displacement control signal as a first measured pressure, and detecting a pressure generated from the proportional electromagnetic valve when the proportional electromagnetic valve is driven with the maximum-side displacement control signal as a second measured pressure,

the calculating unit calculates as learned values a first difference between the minimum-side displacement control pressure and the first measured pressure, and a second difference between the maximum-side displacement control pressure and the second measured pressure, and

the calculating unit calculates a correction amount based on the first and second differences and a displacement command when the displacement command is generated, and corrects a required displacement control pressure required to provide a displacement angle corresponding to the generated displacement command with the correction amount, wherein

the calculating unit calculates the displacement control signal based on the corrected required displacement control pressure with reference to the reference characteristic.

22. (new) A displacement control device, comprising:

a calculating unit for calculating a displacement control signal for driving a proportional electromagnetic valve, based on a displacement command; and

an adjusting unit for adjusting a displacement angle of a hydraulic device by driving the proportional electromagnetic valve with the displacement control signal calculated by the calculating unit, and applying a displacement control pressure generated from the proportional electromagnetic valve to a displacement adjusting device, wherein

the calculating unit calculates the displacement control signal based on the displacement command, referring to a reference characteristic representing a relationship between the displacement command, and a required displacement control signal required for the proportional electromagnetic valve to generate a required displacement control pressure required to provide a displacement angle corresponding to the displacement command, the displacement control device further comprising:

a pressure detector which detects pressures generated from the proportional electromagnetic valve when the proportional electromagnetic valve is driven with a minimum-displacement-side control signal used for learning and a maximum-displacement-side control signal used for learning, respectively, as first and second measured pressures;

a displacement control signal calculating unit, the displacement control signal calculating unit providing a minimum displacement control signal to cause the proportional electromagnetic valve to generate a displacement control pressure corresponding to a minimum displacement angle and a maximum displacement control signal for causing the proportional electromagnetic valve to generate a displacement control pressure corresponding

to a maximum displacement angle, based on a relationship between the minimum-displacement-side and maximum-displacement-side control signals and the first and second measured pressures;

a difference calculating unit, the difference calculating unit calculating a first difference between the minimum displacement control signal and the minimum-displacement-side control signal used for learning, and calculating a second difference between the maximum displacement control signal and the maximum-displacement-side control signal used for learning;

a learned characteristic generating unit, the learned characteristic generating unit generating a learned characteristic representing a relationship between a displacement command, and a required displacement control signal corresponding to the displacement command, based on the reference characteristic and the first and second differences;

a correction amount calculating unit, the correction amount calculating unit calculating a correction amount based on the displacement command, referring to the learned characteristic; and

a displacement control signal correction unit, the displacement control signal correction unit correcting the displacement control signal calculated by the correction amount calculating unit based on the displacement command referring to the reference characteristic, with the correction amount.

23. (new) A construction machine, comprising a displacement control device according to claim 21.

24. (new) A construction machine, comprising a displacement control device according to claim 22.